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AN APPROXIMATE TECHNIQUE FOR THE INTEGRATIONS
OF THE EQUATIONS OF NOTION IN A FIRE ELECTION LASER*

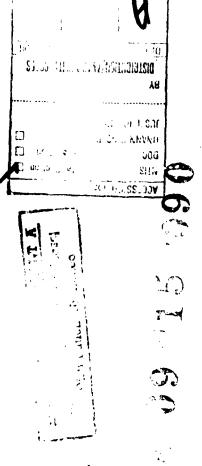
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AN APPROXIMATE TECHNIQUE POR THE INTEGRATIONS OF THE EQUATIONS OF NOTION IN A FIREE ELECTRON LASER

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ABSTRACT

Ms describe an approximation we have used to compute gain, saturation, and electron statistics at high power in the Stanfurd Pree Electron Laser.



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AN APPROXIMATE TECHNIQUE FOR THE INTEGRATIONS OF THE EQUATIONS OF THE ELECTRON LASER

1. Introduction

In the analysis of the free-electron laser (FEL) it is necessary to follow the motion of an electron beam as it cover through a lung periodic magnetic field in the presence of an electronagnetic wave. We are interested in several aspects of the problem: 1) flow much exargy do the electrons transfer to the electromagnetic field?

2) What is the spread in the charge when the electrons? and 3) How do the gain and spread charge when the amplitude of the cave

Whose the optical power density is low, the phase and amplitude of the flaid cannot be defined with precision and it is necessary to amploy a quantum formulation to analyze the evolution of the electron's trajectories. I when the optical power density is large or, alternatively, when the Gnve length is long, the classical approximation can be employed. The cendition for the applicability of the classical approximation can approximation can be formulated as:

where $S=\{c/\delta r\}(g\times H)$ is the optical power density, ω_0 is the optical frequency, λ_q the magnet period and h is Fianck's constant.

Our interest in this paper lies in operation at high power, and we will assume the validity of the classical approximation. It is useful to consider two limiting cases. When the electron density is

large, the coulomb forces between electrons become comparable to the force due to the electric and magnetic fields and, since the gain can be large, the clergy density of the electromagnetic field can changed substantially during the interaction. In this limit, it is not practical to follow the motion of individual electrons and the problem is best pursued by treating the electron distribution as a charged fluid. Microwave power tubes such as klystrons, ragnetrons and traveling wave tubes most commonly operate in this limit.

In the low-current limit the motion of electrons is small the amplitude of their neighbors, and so long as the gain is small the amplitude of the electromagnetic field changes only slightly during the interactional in this case, it is possible to approximate the field as constant and to reduce the problem to the analysis of the motion of a single electron. The single particle approach is applicable when the Debym wavelength measured in the electron rest frame is large in comparison to the optical wavelength:

$$k_{\rm p}^{-1} = \left(\frac{K_{\rm s}}{4\pi n_0 e^2}\right)^{1/2} > \lambda \tag{2}$$

and when the gain per pass is less than 3 in. In contrast to the situation in microwave power tubes, the electron duesity in the rest frame is typically small in dovices involving the interaction of relativistic electrons at optical wavelengths. Devices such as the free-electron laser which operate at infrared and visible wavelengths can be described quite adequately by the single particle approximation.

A number of methods have been applied to analyze operations in

grated the Lorentz force equations in the single particle limit for a microwave power tube, the ubitron. A number of authors have also developed numerical solutions to the collisionless Boltzman equations. Get the electron distribution in a FEL. The Boltzmann approach has the advantage of yield ig a direct result for the distribution function, but the causal consection between the electrons' motion and the initial conditions is suppressed. Finally, Coison, Smambini and Remieri⁶, and haier and Milstein have derived an elegant transformation to relate the electrons' motion is a free-electron laser to the motion of a pravitational field. This transformation has been a powerful tool for the description of laser operation in both the small signal and saturation regimes.

The method described in this paper was first employed by Maday and Deacon. This technique relates the solution of the Lorentz force equation in the presence of an optical field to the solutions of the force equation when only the de magnetic field is present. The advantage of the technique is that it is directly applicable to the analysis of electron motion in periodic magnets of arbitrary geometry and it is well adapted for use in mamerical calculations. Qualitatively, the method is interesting because the physical arguments justifying the approximation indicate that the laser interaction does not fundamentally sliter the character of the electrons: trajectories in the periodic field. We will find that the principal effect of the optical field is simply to accelerate the electrons along trajectories which are locally indistinguishable from the trajectories they would follow when only the de field is present.

Description of the Approximation

In a free-electron laser an electron beam is made to move through a spatially periodic transverse magnetic field. To be specific, we will assume that the electrons move along the 2 axis mad that the magnetic field can be represented in the form:

$$\frac{1}{2}_0 = \frac{1}{2} = \frac{1}{2} = \frac{2\pi}{4} = \frac{2\pi}{4} = \frac{3\pi}{4} =$$

where $\lambda_{\bf q}$ is the period of the field and the censtant vector ${\bf B}_{\bf q}$ can be real or complex depending on the polarization. The transverse magnetic field causes the electrons' transverse position to escillate with the period of the magnet. For a circularly polarized field the electrons will move in a belical trajectory, whereas a linear transverse field will result in planar motion.

The momentum $\frac{1}{20}$ and velocity $\frac{1}{20}c$ of an electron moving through the field in the absence of an optical field must satisfy the equation:

This can be rewritten in the form:

$$\sqrt{\gamma^2-1} \frac{d\hat{\theta}}{dt} = (\frac{1}{4\pi}) \frac{1}{2} \times \frac{3}{2} \tag{5}$$

where γmc^2 is the electron mass evergy, β_0 is the instantaneous direction of motion of the electrons ($|\beta_0|$ m l), and we have made use of the identities

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The objective is to determine the effect of the optical field enths trajectories. We will assume that the optical field can be represented as a plane wave:

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where \underline{K} is the propagation vector, $\mathbf{u} = \mathbf{k}/c$ and $\underline{\mathbf{g}}_0$ can be real or complex, depending on the polarization. In the presence of the optical field the electron momentum p and velocity β must satisfy the equation:

We will show that the solution to equation (5) can be approximated by the solution to the modified equations:

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The first equation relates the rate of change of \hat{B} to \hat{B} and \hat{B}_0 . It is identical to the equation governing the motion of electrons in the static field when the optical field is absent. The radius of curvature of an electron with a given vector velucity in this approximation with the therefore be identical to the curvature of an electron with the velocity when the optical field is absent. Equation (96) relates the rate of change of emergy to the dot product of the electron velocity and the electric field. Equation (96) would be exact if $c\hat{g}$ were the actual velocity.

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that it is frequently possible to develop a general solution, we note motion of an electron through a static periodic field in which \tilde{g} is expressed as a function of the energy and position of the electron and the period, polarization, and amplitude of the static field. This means that the solution to equation (9s) will typically be available in exther analytic or tabular form and only equation (9b) will mead to be integrated, substantially reducing the effort required to integrate the equations of motion.

3. Estimation of Error

To estimate the error generated by the approximation we will develop a differential equation for the error term θ_p , the difference between the exact solution $p_(t)$ and the approximation volution $p_g(t)$. If θ_p is defined:

them de satisfies the differential equation:

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where r is the exact electron position at the time t and cg is the exact velocity. We have defined $\gamma_{a}mc^{2}$ and c_{2a}^{2} as the approximate electron mass-every and velocity, consistent with the designation of. γ_{a} as the approximate momentum, and have used equation (8) to express dg/dt in terms of the fields \tilde{x}_{a} , \tilde{x}_{a} and \tilde{x}_{a} .

If \underline{r} and \underline{g} were known, equation (11) could be integrated to obtain $d\underline{p}(t)$ using the values of $T_{\underline{g}}$ and $\underline{g}_{\underline{g}}$ computed from the approximation. Although we do not know \underline{r} and $\underline{g}_{\underline{g}}$, these quantities can be expressed in terms of $\underline{r}_{\underline{g}}$ and $\underline{g}_{\underline{g}}$, $\underline{g}_{\underline{r}}$ and $\underline{g}_{\underline{g}}$, $\underline{g}_{\underline{r}}$ and $\underline{g}_{\underline{g}}$, $\underline{g}_{\underline{r}}$ and $\underline{g}_{\underline{g}}$, where $\underline{r}_{\underline{g}}$ is the approximate position of the electron and $\underline{g}_{\underline{g}}$ and $\underline{g}_{\underline{g}}$, where $\underline{r}_{\underline{g}}$ is the approximate position of

$$\underline{x}(t) = \underline{x}_{\mathbf{g}}(t) + \delta \underline{x}(t)$$

$$\tilde{\mathbf{g}}(\mathbf{t}) = \tilde{\mathbf{g}}_{\mathbf{t}}(\mathbf{t}) + \delta \tilde{\mathbf{g}}(\mathbf{t}) . \tag{12}$$

r and h can be defined in terms of h and Ya:

and fr and dg can similarly be expressed in terms of dp:

$$(\frac{\delta g}{v_{\rm e}} \sim \frac{\delta p}{v_{\rm e}} \sim (\frac{g}{s_{\rm e}} - \frac{g}{s_{\rm e}} - \frac{\delta p}{v_{\rm e}})$$

Under the assumption that by is small in comparison to the regnet period and optical wavelength, the fields can be expended as:

$$\mathbf{P}_{\mathbf{G}}(\mathbf{r}) = (1 \cdot 6\mathbf{r} \cdot \mathbf{V}) \ \mathbf{P}_{\mathbf{G}}(\mathbf{r}_{\mathbf{g}})$$

$$\tilde{\mathbf{g}}(\tilde{\mathbf{r}},t) \approx (1 + \delta \tilde{\mathbf{r}} \cdot \tilde{\mathbf{v}}) \quad \tilde{\mathbf{g}}(\tilde{\mathbf{r}}_{\mathbf{a}},t)$$

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$$\hat{\mathbf{J}}(\hat{\mathbf{z}}, t) = (1 + \hat{\mathbf{d}}_{\hat{\mathbf{z}}}, \hat{\mathbf{v}}) - \hat{\mathbf{J}}(\hat{\mathbf{z}}_{\hat{\mathbf{z}}}, t)$$

end equation (11) can be rewritten as:

$$\frac{d\delta_{\overline{k}}}{d\overline{t}} = 0 \left[\overline{\underline{t}}(\underline{r}_{\underline{k}}, t) + \underline{\underline{\theta}}_{\underline{k}} \times \overline{\underline{y}}(\underline{r}_{\underline{k}}, t) \right] + 0 \underline{\underline{\theta}}_{\underline{k}} \times \overline{\underline{b}}_{\underline{k}}(\underline{r}_{\underline{k}}, t)$$

$$- (\omega_c) \sqrt{\gamma_a^2 - 1} - \frac{3\hat{s}_a}{3\epsilon} + \frac{\hat{s}_a \gamma_a}{\sqrt{\gamma_a^2 - 1}} - \frac{3\gamma_a}{3\epsilon} \right] + o \left((\delta_{\underline{L}} \cdot \underline{\Psi}) \tilde{E}(\underline{r}_a, \epsilon) \right)$$

(91)

Since or and og can be expressed in terms of op and its integral, as shown in equation (14), equation (16) constitutes an integro-differential equation for op. Given the values \mathbf{p}_a , $\hat{\mathbf{p}}_a$ and \mathbf{r}_a from the approximation, equation (16) can be integrated to obtain the x merical value of orch

of the error terms.

The driving terms in equation (16) are:

$$6\left[\mathbb{E}\left(\underline{\xi}_{\mathbf{a}},\xi\right) + \hat{\theta}_{\mathbf{a}} \times \mathbb{E}\left(\underline{\xi}_{\mathbf{a}},t\right)\right] + e\hat{\theta}_{\mathbf{a}} \times \mathbb{E}_{0}\left(\underline{\xi}_{\mathbf{a}},t\right) \\ - \log\left[\sqrt{\gamma_{\mathbf{a}}^{2}-1} \quad \frac{3\hat{\theta}_{\mathbf{a}}}{3t} - \frac{\hat{\theta}_{\mathbf{a}}\gamma_{\mathbf{a}}}{\sqrt{\gamma_{\mathbf{a}}^{2}-1}} \quad \frac{3\gamma_{\mathbf{a}}}{3t}\right]. \tag{17}$$

If this sum were equal to zero, equation (16) could be satisfied by setting $\delta p_{\rm s} = \delta g_{\rm s} = 0$ and $p_{\rm s}$ would be an exact solution. Although the individual terms in equation (17) will not be zero, we can show that the terms cancel to the order of $1/\gamma^2$. It is immediately seem from equation (9s) that $\left(\frac{e}{mc}\right) \frac{g_{\rm s}}{g_{\rm s}} \times \frac{g_{\rm s}}{g_{\rm s}} (r_{\rm s}, \tau) - \sqrt{\gamma_{\rm s}^2 - 1} = 3 \hat{g}_{\rm s}/4 t = 0$. To demonstrate the cancellation of the remaining terms, we will define $g_{\rm s} = g_{\rm s} = g_{$

$$\bullet [\widetilde{E}(\underline{x}_{\underline{a}}, t) + \underline{b}_{\underline{a}}^{\times} \ \widetilde{b}(\underline{x}_{\underline{a}}, t)] - (ac) \frac{\overline{b}_{\underline{a}}^{\times}}{\sqrt{\gamma_{\underline{a}}^{2} - 1}} \cdot \frac{\partial \gamma_{\underline{a}}}{\partial \overline{c}} \\
= \bullet [(1 - \underline{b}_{\underline{a}})\widetilde{\underline{c}} + (1 - \frac{\underline{b}_{\underline{a}}^{*}}{\underline{b}_{\underline{a}}^{*}}) \ (\underline{b} \cdot \underline{\underline{c}})^{2} - \frac{1}{\underline{b}_{\underline{a}}^{*}} \ (\underline{b} \cdot \underline{\underline{c}}) \underline{b}_{\underline{1}}] .$$
(13)

The magnitude of the terms on the right hand side of equation (18) is fixed by the magnitudes of \hat{h}_{\parallel} and \hat{h}_{\parallel} , the longitudinal and transverse velocities for an electron of the given energy soving through the static field B.

The canonical momentum of an electron moving through the

interaction region is $\frac{aA}{c}$ where A is the vector potential. Given the specifications of the magnetic field in equation (3) and the assumption $\hat{k} = \ell$, the lagrangian $(p + \frac{aA}{c})^2$ for an electron in the interaction region is independent of the transverse co-ordinates x and y. The transverse canonical momentum is, therefore, a constant of the motion. For typical operation conditions we can assume that the transverse canonical momentum $(p > \frac{aA}{c})_{\perp} = 0$. This follows frest the requirement that the electron's everage transverse kinetic momentum has to be minimized to limit the spread of the beam in the interaction region and to minimize the effect of transverse momentum on operating frequency and lineshape. If the transverse canonical momentum is zero, the transverse emponent of the kinetic annual missing $\frac{aA}{c}$, and we have for the transverse component of $\frac{aA}{c}$, and we have for the transverse component of $\frac{aA}{c}$.

$$\hat{\theta}_1 = (\hat{\theta} \cdot \hat{\theta}) \hat{z} = \frac{p - (p \cdot \hat{\theta}) \hat{z}}{\gamma mc} = \frac{cA_{\perp}}{\gamma mc^2}.$$
 (19)

Given eq. (6), the magnitude of B_{\perp} and B_{\parallel} is determined by the vector potential that static field B_{o} . For a field with a period of λ_{q} and an amplitude B_{o} , the amplitude of the vector priestial will be of the order of $(\lambda_{q}/2\pi)B_{o}$. For the circularly polarized magnetic field in the Stanford PEL:

$$|B_1| = \frac{e}{\gamma_{a} m^2} \frac{\lambda_a B_0}{2\pi}$$

$$|B_1| = \sqrt{B^2 B_1^2} = 1 - \frac{1}{2\gamma^2} \left[1 + \left(\frac{1}{2\pi}\right)^2 \frac{\lambda_a \frac{2}{2} B^2}{m^2}\right] \tag{20}$$

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If we assume these values for θ_{j} and θ_{j} , the individual terms in equation (18) have the form:

$$0(1-f_{1})\tilde{g} = \frac{1}{2\gamma_{0}} \left[1 \cdot \left(\frac{\lambda_{0}-\delta}{2\pi nc^{2}}\right)^{2}\right]\tilde{g}$$

$$\frac{1}{g_{0}^{2}} \left(\tilde{g} \cdot \tilde{g}\right)\tilde{g}_{1} = \frac{1}{\gamma_{0}^{2}} \left(\frac{\lambda_{0}-\delta}{2\pi nc^{2}}\right)^{2} \frac{(\tilde{g} \cdot \tilde{g}_{1})\tilde{g}_{1}}{|\eta_{1}|^{2}}$$

$$0(1-\frac{\eta_{1}}{g_{1}^{2}})(\tilde{g} \cdot \tilde{g}_{2})\tilde{g} = -\frac{1}{2\gamma_{0}^{2}} \left(\frac{\lambda_{0}-\delta}{2\pi nc^{2}}\right)^{2} \frac{(\tilde{g} \cdot \tilde{g}_{1})\tilde{g}_{1}}{|\eta_{1}|^{2}}\tilde{g}.$$

$$(21)$$

The largest of these terms is of order of/ γ^2 . We note that, although the numerical coefficients on the right hand side in equation (21) follow from the choice of circular polarization for the magnetic field, the cancellation of the terms to order $1/\gamma^2$ follows from the definition of the terms and is independent of

To estimate the magnitude of do using equation (16) we will suggest the torms proportional to do and 5g and apply the triangle and Cauchay-Schmartz langualities to generate an upper bound for [do]. The neglect of the terms containing by and 6g is justified by the observation that do and 6g are of order 3p/7 or 4p/7 and that the terms containing do and 6g are linear in the field amplitudes B, and B₀. The fractional error introduced in 4p by the neglect of 6g and 6g is equation (16) will therefore be at most of order 2/7 or b_/7 and will approach zero in the relativistic limit.

If equation (21) is used to reduce the driving terms in equation (16) and the terms proportional to by and 6g are dropped, we obtain:

$$\frac{d\theta_{2}}{dc} = \frac{1}{T_{a}} \left(\frac{1}{2} \left[1 + \left(\frac{\Lambda_{a}^{a} \theta_{2}}{2 m_{a}^{a}} \right)^{2} \right] \frac{(\tilde{a} \cdot \tilde{b}_{1}) h_{1}}{2 m_{a}^{a}} \right)^{2} \frac{(\tilde{b} \cdot \tilde{b}_{1}) h_{1}}{|h_{1}|^{2}}$$

$$- \frac{1}{2T_{a}} \left(\frac{\Lambda_{a}^{a} \theta_{2}}{2 m_{a}^{a}} \right) \left[1 + \left(\frac{\Lambda_{a}^{a} \theta_{2}}{2 m_{a}^{a}} \right)^{2} \right] \frac{(\tilde{b} \cdot \tilde{b}_{1}) h_{1}}{|h_{1}|^{2}}$$

$$(22)$$

If we define $\delta_{2j} \equiv (\delta_{p} \cdot f) f$ and $\delta_{2j} \equiv \delta_{p} - \delta_{2j}$, equation (22) can be further reduced to the equations:

$$\frac{d}{dt} \theta_{11} \cdots \frac{e}{3\gamma_{n}} \left(\frac{d}{2\pi n c} \frac{d}{2} \right) \left(1 - \left(\frac{\lambda_{n} - e}{2\pi n c} \right)^{2} \right) \frac{(E - f_{1})}{|f_{1}|} t$$
(236)

$$\frac{d}{dt} \Phi_{L} = \frac{e}{V_{L}} \left(\frac{1}{2} \left[1 + \left(\frac{\lambda_{0} \Phi_{L}^{2}}{2 m c^{2}} \right)^{2} \right] \frac{1}{8} + \left(\frac{\lambda_{0} \Phi_{L}^{2}}{2 m c^{2}} \right)^{2} \frac{(\tilde{g} - \frac{h}{h})}{|h_{L}|^{2}} \times \frac{h}{h} \right). \quad (239)$$

Applying the triangle and Cauchey-Schmarts inequalities we have:

$$|\Phi_{\underline{L}}(T)| < \frac{1}{T_0} \int_0^T dt \left(\frac{1}{2} \left[1 + \left(\frac{\lambda_0 \theta}{2\pi e^2} \right)^2 \right] |\underline{e}| + \left(\frac{\lambda_0 \theta}{2\pi e^2} \right)^2 \frac{|\underline{e}| \underline{h}|}{|\underline{h}_1|} \right)$$

$$< \frac{1}{T_0} \left(\frac{\lambda_0 \theta}{2\pi e^2} \right)^2 \left(\frac{\lambda_0 \theta}{2\pi e^2} \right)^2 |\underline{e}| T$$

where the interaction is assumed to start at t = 0 and to end at t = T, and $\|E\|$ and $\|E\|$ are understood to be the maximum values of the field and transverse velocity in the interaction region.

The actual magnitudes of $d_{\rm pl}$ and $d_{\rm pl}$ will be influenced by the time dependence of the right hard side of equation (23). If the right

hand side is mearly constant in time as in the case of $\frac{d}{dt}$ θ_{DL} [Eq. (23a)], δp_{\parallel} can approach the magnitude of the upper bound derived in equation (24). But if the right hand side oscillates rapidly during the interaction as in the case of $\frac{d}{dt}$ δp_{\parallel} [Eq. (23b)], the upper bound in equation (24) will be a conservative estimate of the magnitude. The right hand side of equation (23b) oscillates with the unguet period and in this case a better estimate of the magnitude of δp_{\parallel} could plausibly be attained by setting T equal to the time required to traverse one magnet period.

Given the upper bounds from δp_{\parallel} and δp_{\perp} from equation (24), we can easily derive upper bounds for the error in energy δB and for the position error δr . From $E^2 = \left(p_{\parallel} + \delta p\right)^2 c^2 + m^2 c^4$ we have:

$$\frac{dB}{B} = \frac{2p_{a} \cdot \delta_{L}}{2 + B^{2} c^{2}} . \tag{25}$$

Mile from equation (14) we have:

$$|\delta_{2_{1}}| < cr |\delta_{2_{1}}| = cr \cdot \frac{|\delta_{2_{1}}|}{\gamma_{2_{1}}}$$

$$|\delta_{2_{1}}| < cr |\delta_{2_{1}}| = cr \cdot \frac{|\delta_{2_{1}}|}{\gamma_{2_{1}}}$$
(26)

where δg_1 , δg_2 , δg_3 and δg_2 have been defined consistent with the previous definitions of δp_1 and δp_2 as the projections on the x-axis and on the plane normal 1. We note that the relationship utilized in equation (26) between the longitudinal components of δp and δp_2 and the transverse components of these vectors differ because the

increment of velocity is in one case parallel to the direction of motion and in the other case it is assumed to be normal to p.

For the Stanford Free-Electron Laser, which uperated with a 43 MeV electron beam at a mavelength of 3 aicrons, the magnet period wis 3.2 cm, and the interaction length was 5.2 meters. The power density in the interaction region at saturation was approximately 10⁷ watts/cm². Using equation (20) to compute B_g and B_g for the helical magnet and equation (24) to compute the upper bounds to bpg and bpg. we obtain for bp, dE and degree saturation:

$$\frac{\delta E}{E} < 3.2 \times 10^{-6} \tag{27}$$

We note that the error in δr_{ij} is less than 12 Å, consistent with time assumption that δr_{ij} is small in comparison to the optical wavelength. The fractional error $\delta E/E$ in energy is less them 3.2 × 10⁻⁶. By comparison, the average fractional energy loss and 305 spread in energy for these operating conditions are of the erder of 1 × 10⁻² (see Figures 2 and 3). It is apparent that the errors in the axial

position and measurem computed weing this approximation are very mail.

The limits on dr_1 and dp_1 are not so impressive. In part, the problem arises from the escillatory nature of the integrand in equation (236). The integrand reverses sign every magnet period whereas, in the upper bound developed using the triangle inequality is equation (24), the integrand is taken to be positive dofinite. Undertunately, the enly reliable means to estimate the size of dp_1 and dr_1 in comparison to the upper bounds in equation (27) would be to integrate equations (14b) and (23b), a technique which can be applied eaty on a case-by-case basis.

the approximation is entirely adequate for the analysis of the energy radiated by the electrons during their passage through the periodic field.

We cannot be so confident of the approximation's representation of the effect of the interaction on the transverse measurem of the electrons. The use of the approximation is cases in which the transverse measurem is of interest vill have to be justified

by the emplicit integrations for \$\tilde{\rho}_1\$ and \$\tilde{\rho}_1^2.

4. Application to the Analysis of FEL Operation

As an example of an application of this technique, we can malyze the operative of the Stanford Pres-Electron Leser in the single pass configuration and examine the effect of variation of the angment period on the gain and electron meanutes spectrum. If the

circularly polarized magnetic field is empressed in the form:

$$\frac{3}{2}_{0} - \frac{3}{6} \left[\frac{3 \cos \left(\frac{2 \pi z}{\lambda_{0}} \right)}{\lambda_{0}} + \frac{9 \pi i \pi \left(\frac{2 \pi z}{\lambda_{0}} \right)}{\lambda_{0}} \right] \right] \tag{29}$$

and we restrict consideration to trajectories in which the transverse canonical momentum is zero, the solution to equation (a) has the form:

$$\hat{g}(t) = (1 - \frac{1}{\sqrt{2}} (1 - (\frac{1}{\sqrt{2}})^2 (\frac{\lambda_1^{-2} e^{-\beta_2}}{2\pi \gamma m^2}))^{1/2} + (\frac{1}{\sqrt{2}} e^{-\beta_2})^{-\beta_2} (3\cos(\frac{2\pi \epsilon}{\lambda_1^2}) - 9 \sin(\frac{2\pi \epsilon}{\lambda_1^2}))$$

$$\hat{g}_{\parallel} = (1 - \frac{1}{2\gamma_1^2} (1 - (\frac{1}{2\pi})^2 (\frac{\lambda_1^{-2} e^{-\beta_2}}{2\pi \gamma m^2})) > (29)$$

to moto that the magnitude of A₂ and A₂ depend only on A₂. B₆ and Y₆ med Y₆ and Y₆ are taken and the position. From equation (M):

where 0 is the phase angle between the tremsverse mannium and the electric field:

$$0 \cdot (ac - kz) - \frac{2rz}{\lambda} \quad . \tag{31}$$

To integrate equation (30), we need to know the dependence of 0 on time. The time derivative of 0 cm be expressed as:

$$\frac{d\theta}{dt} = \omega - (k + \frac{2\pi}{4}) \beta_{\parallel} c$$

$$= \omega - c(k + \frac{2\pi}{4}) (1 - \frac{1}{12} \left[1 + \left(\frac{1}{2\pi} \right)^2 \right] \frac{\lambda_{\parallel}^2 r_{\parallel} B^2}{4c^2} \right])^{1/2} .$$

The time derivatives of γ_α and 0 can be converted to derivatives in z by division by β_{ij} c, leading to the coupled squathons:

in which β_{\parallel} and β_{\perp} vary with γ_{a} according to equation (29). This system of equations can be integrated by elementary massrical sethods. If the electron energy is close to the "resonance energy" γ_{x}^{BC}

$$\omega = c(k + \frac{2\pi}{4}) \left(1 + \frac{1}{V_T^2} \left[1 + \left(\frac{1}{2\pi}\right)^2 \left(\frac{A_T c^{-1}}{ac^2}\right)\right]\right)^{1/2}$$
 (34)

and Yr > 1, the derivative do/dt can be approximated by:

$$\frac{d\theta}{dt} = c(k + \frac{2\pi}{\lambda}) \left[1 + \left(\frac{1}{2\pi} \right)^2 \left(\frac{\lambda^2 r_0 B^2}{r_0^2} \right) \frac{(\gamma - \gamma_z)}{\gamma_z} \right]$$
(35)

Equation (35) can be used to express $d\gamma_{\rm p}/dt$ in terms of $d^2\theta/dt^2$. We note that Colson's pendulum equation can be obtained by combining this result with Eq. (30).

We note also that it is possible to use equation (9) to analyze the effects of variations in the magnitude of B_{0} and the period of

the static field. If the field strength and period wary with z, the vector potential will have the form:

$$\tilde{A}(z) = \frac{\lambda_{ij}(z)}{2\pi} = \frac{b_{o}(z)}{2} \left[\frac{2\pi z}{\sqrt{q(z)}} \right] + \frac{2\pi i n}{\sqrt{q(z)}} \right]. \tag{36}$$

If A is assumed to be independent of x and y, the transferse COL, Japans of the canonical momentum remains a constant of the motion and the velocity \hat{A}_C can be computed using equation (29) setting B = B_0(3) and λ_{ij} = $\lambda_{ij}(z)$. The magnet period at:st also be made a function of position in equations (32) and (35) for d0/dt and d0/dz. With these modifications, equations (33) can be integrated directly to compute the approximate electron energy and phase as functions of z.

while the initial value of Y_B is fixed by the energy with which the electrons enter the interaction region, the laitial value of 0 is not determined for a continuous electron beam. The change in the value of 10 at the end of the interaction region as 0 (t = 0) varies between 0 and 2x leads to a spread in energy of the electrons energing from the laser. The mean electron energy loss and the DAS energy spread can be computed by means of the appropriate averages over the inital phase.

The data in Figures 1-4 illustrate the application of the approximation. The data in Figure 1 shows a histogram for the fine! electron energy at an optical power dencity of 10⁷ watts/cm² for the constant period helix used in the Stanford PEL. The initial phase was varied in steps of #/100 between 0 and 24. Figure 2 shows the Jependence of the maximum available gain on optical power density

The second secon

for the Stanford magnet. Note that the available gain falls off at 1/5 at high power. Pigures 3 and 4 show the dependence of gain and the spread on electron energy for two different magnet geometries. The data in Pigure 3 shows a simple constant period helix. In Figure 4 the spread has been reduced and the gain increased by systematically increasing the magnet period starting with 5.20 centimeters and ending with 5.22 centimeters at the end of the interaction region.

We thenk Dr. W. B. Colson for his commuts concerning this
obline.

FIGHE CATION

figure 1: The figure shows a histogram for the final electron energy for the Stanford Free-Electron Laser computed using the approximation described in the text. The horizontal axis indicates the final electron energy. The vertical axis indicates the manher of electrons falling into each energy bin as the initial phase was varied between zero and 2r in stope of 8/50 radians. The magnet period was 5.2 cm, the magnet langth 5.2 meters, and the magnetic field strangth 2.3 kiloganss. The eptical wavelength was 34 and the optical power density 10 meta/cm². The initial electron energy was 42.19 MeV and was chosen to maximise the pain evaluable at this power density.

Figure 2: The figure shows the dependence of the fractional gain perpass on the optical power density for the magnet used in the Stanford Pil. The data is for an optical wavelength of 3s.

Figure 3: The figure shows the dependence on electron energy of relative optical gain and the MG spread in electron energy far the magnet in the Stanford Fil. The data is for an optical wavelongth of 39 and an optical power density of 10⁷ units/cm².

Figure 4: The figures shows the dependence on electron energy of the relative optical gain and the RMS spread is electron energy.

The data is for a 160 period magnet in which the period was increased linearly from 5.20 cm at the start of the interaction region to 5.22 cm at the east. The optical wavelength and power demaity are the same as in Figure 5.

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SYNGOLS

Physical Constants

- e = electron charge (4.8 x 10⁻¹⁰ statcoulombs)
 - = electron mass (9.11 x 10^{-28} grams)
- = speed of light (3 x 10 th sec 1)
- = Planck's constant (1.05 x 10^{-27} erg-sec)
- $K = Boltzmenn's constant (1.38 x 10^{-16} erg eK^{-1})$

Electron Coordinates

- r = exact electron position
- r = approximate electron position calculated using approximation
 described in text for analysis of electron motion in
 presence of optical field.
- r = r r = position error
- or | = (6r.2)2 = longitudinal position error
 - or = or-or = transverse position error
- = I/c = exact normalized electron velocity
- . . normalized electron velocity when optical field is absent
- $\frac{1}{3}_0 = \frac{1}{2}_0/|\frac{1}{2}_0|$ = unit vector for normalized valocity when optical field is absent
- g = approximate normalized velocity, calculated using approximation described in text to analyzo electron motion in presence of optical field.
 - g = (g .2)2 = normalized approximate longitudinal velocity
 - B = B B = normalized approximate transverse velocity
 - dg = g g = normelized velocity error
- 6g = (6g.t)f = normalized longitudinal velocity error
 - 68 = 68 68 m normalized transverse velocity error

- \mathbf{p} = exact electron nomentum (gn-cm-sec⁻¹)
- P. electron momentum when optical fleid is absent
- approximate electron momentum calculated using approximation described in text for analysis of electron motion in presence of oprical field.
- P. P. P. " BONNEUS OTTOR
- de a (6p.f.t a longitudinal momentum error
- de de transverse momentum error
- $r = \sqrt{r^2 + r^2}$ we a caset normalized electron mass-energy
- approximate electron mass-energy, calculated using approximation described in text for analysis of electron motion in presence of optical field.
- T = Y Y = E = error in normalized energy

Optical Maid Coordinates

- u = optical froquency (sec⁻¹)
- r optical wave vector (ca.1)
- k k/|k| mait nave vector
- E optical electric field (stat colts cm-1)
- optical magnetic fleld (gauss)
- polarization vector for optical electric field
- S_{1ab} optical power density (ergs ca^{-2} sec⁻¹)

Spect Genetry

- . . mgnet period (ca)
- . length (ca)
- . . static megnetic field (grass)
- . polarization vector for static magnetic flaid.

- vector potential for static magnetic field
- $A_1 = A_2 (A^*2)^2$ = transverse component of vector potential

Miscel leseous

- dummy veriable for time
- total interaction time (sec)
- a debye wave number
- electron density (cm. 3)
- · temperature (*I)

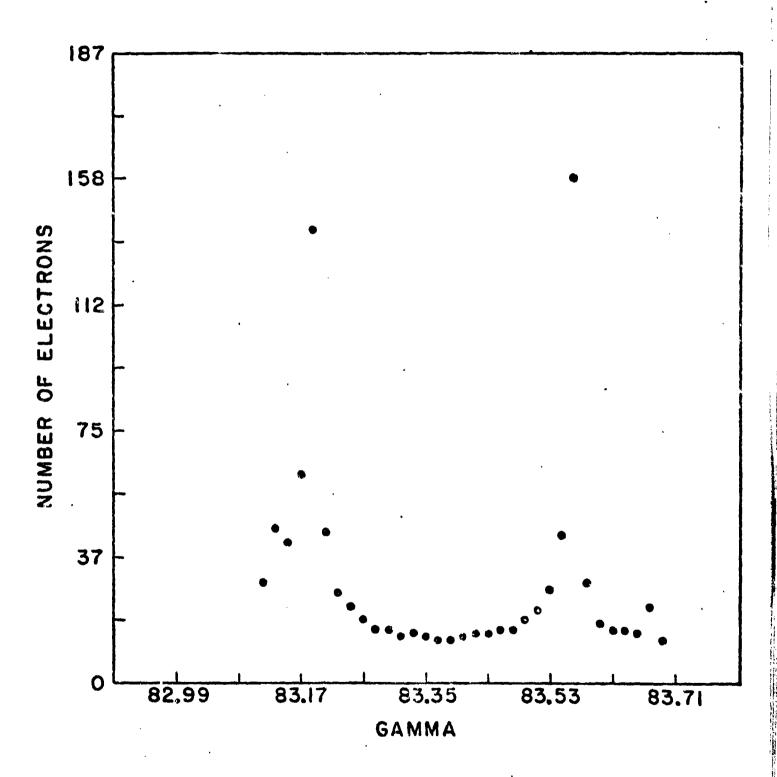


Figure 1

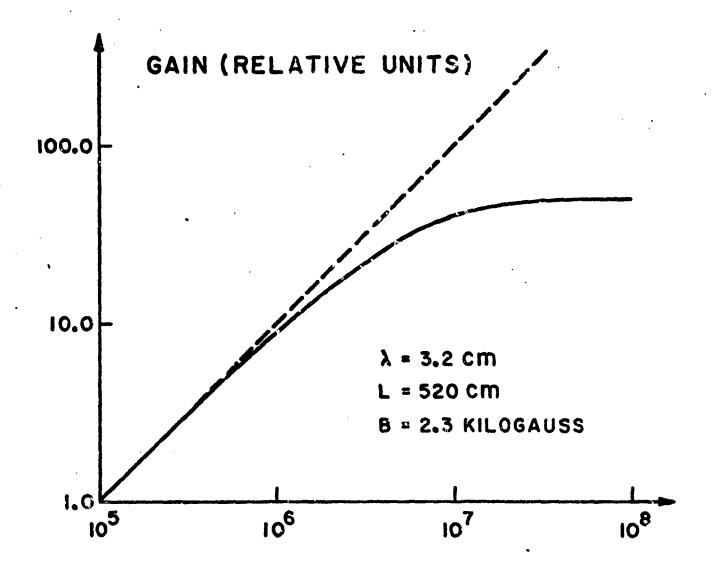


Figure 2

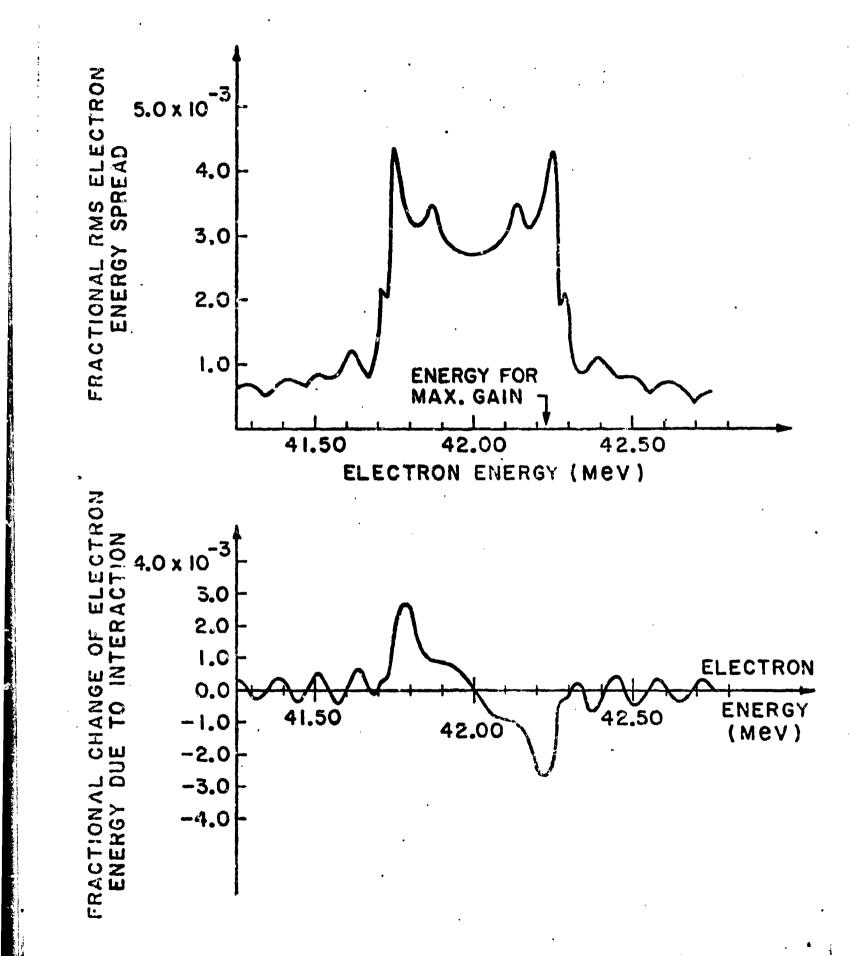


Figure 3

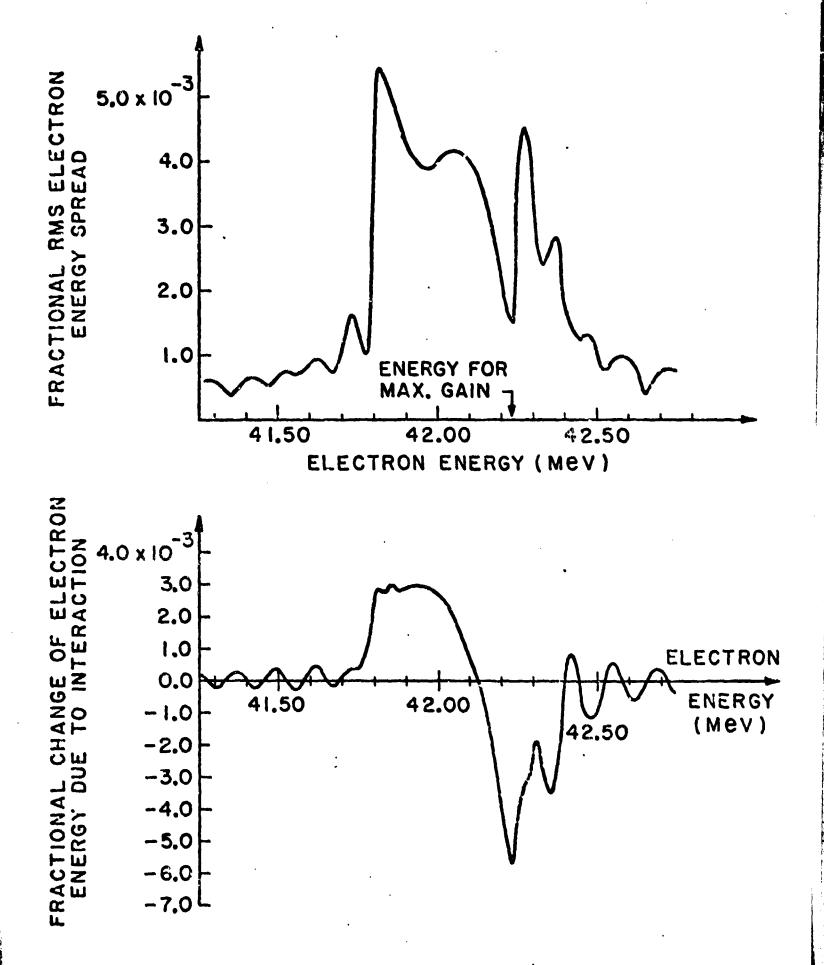


Figure 4

HEPL 824

September 1978

ONE DIMENSIONAL MONTE CARLO ANALYSIS OF A FREE ELECTRON LASER IN A STORAGE RING* L. R. Elias, J. M. J. Madey, and T. I. Smith

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ABSTRACT

librium energy spread, bunch length, and average energy radiated We report the results of a montecarlo analysis of the equiby electrons in a storage ring free electron laser.

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Introduction

The present report deals only with computer data obtained before February 15, 1978 and does not discuss the operations of the FEL in a storage ring when transverse field gradients (i.e., gain expansion) are allowed in the FEL magnet. A subsequent report will discuss these effects in letail.

This report contains studies of energy and phase dynamics of a single electron interacting with a free electron laser (FEL) oscilliator operating in an electron storage ring. The studies include numerical integration of the energy and phase equations of motion to calculate equilibrium values of a) electron energy spread,

b) electron phase spread (electron bunch length), and c) average electron energy converted into laser radiation. The non-equilibrium motion of the electron energy is analyzed by means of the energy autocordiation which yields, among other things, an effective damping rate for the electron energy motion. In addition, the energy autocorrelation function allows to qualitatively describe the exchanisms involved in the damping and excitation of electron energy oscillations and fluctuations. Storage ring simulations for fire different magnet designs operating at optical power densities uplos saturation were studied. The results are presented here.

Description of the Problem

A complete discussion of the physics of electron storage rings can be found in reference 1. Figure 1 shows the three basic components of a FEL oscillator in a storage ring. There are: a) a free electron laser oscillator, b) a radio frequency cavity, and c) bending magnets.

The bending magnets guide the electrons into racetrack-type closed orbits whose lengths are proportional to the electron's energy. Two such c-bits are shown in figure 1. Since the velocity of a relativistic electron is very close to the velocity of light, then the revolution time of the electron moving along one of its closed orbits is also proportional to the energy of the electron.

The FEL oscillator extracts energy from the circulating electron and converts it into laser radiation. To maintain equilibrium the energy lost by the electron is replaced by means of a radio frequency or microwave cavity. The amount of energy gained by the electron depends on its time of arrival to the RF cavity. The phase and frequency of the RF field in the cavity is adjusted to accelerate the early-arriving, low energy electrons more than the late-arriving, high energy electrons.

If the energy fluctuations resulting from the interaction of the electrons with the FEL oscillator were neglected, the problem of designing a FEL storage ring operating at high laser power and high efficiency would be considerably simplified. In equilibrium, the exact amount of considerably simplified. In equilibrium, would be exactly replaced by the RF cavity and the electron motion would be stable.

In a real FEL storage ring machine an electron may lose or gain energy from the FEL depending on the optical phase with which the electron enters the laser interaction region.

Although, in principle, the classical trajectory of an electron can be determined with arbitrary accuracy, in a real machine whose

dimensions are many optical wavelengths (typically > 10⁷ A) the position of the electron can be determined with only a limited precision. The assumption made in the present analysis is that the precision with which the electron position is determined at the entrance to the FEL is larger than one optical wavelength and at a result the phase with which the electron interacts with the optical wave in the FEL assumes random values uniformly distributed in the interval [0, 2m] on every pass. With this assumption the FEL behaves as a source of fluctuations in electron energy. However, averaged over input phases, the FEL also profides damping of energy fluctuations. If the damping rate of energy fluctuations generated by the FEL is always smaller than the rate at which it excites energy fluctuations, then the energy spread in the storage ring will grow without limit, making the efficient operation of a free electron laser in a storage ring virtually impossible.

The most important result presented in this port is that, for the FEL magnet designs studied in the storage ring simulations, the electron energy spread does not increase without limit. The FEL in conjunction with the other components of the storage ring is capable of damping the electron energy fluctuations that it produces, but the final equilibrium energy spread generated is as large as the energy of the FEL gain-absorption curve. As a result the FEL can operate in a storage ring only at reduced laser power and low

The Free Electron Laser - Lineshape Simulations

The interaction of an electron with the Free Electron Laser can be described classically in terms of the work done by the electric field of the optical radiation on the electron as it moves through the FEL periodic static magnetic field.

Using the Lorentz force equations it is straightforward to show that the net change in energy 6 γ (in units of mc²) of an electron as it completes one pass through the FEL is given by:

$$\delta_{Y} = \frac{q_{z}}{2} \int \frac{E_{R} \cdot \tilde{V}}{V_{z}} dz \qquad (3)$$

where:

$$\vec{E}_{R}$$
 = Electric field of optical radiation \vec{V}_{X} = electron velocity vector \vec{r}_{X} + $\hat{I}V_{y}$ + $\hat{k}V_{g}$. L = length of interaction region.

For example, for a circularly plane polarized radiation field of wavelength λ and a helically wound ungmet of period $\lambda_{\bf k'}$ equation (1) becomes

$$\delta_{Y} = \frac{qE_{R}}{mc^{2}} \int_{0}^{L} \frac{V_{\perp}}{V_{z}} \cos(\theta) dz$$
 (2)

where

$$\theta = \theta_0 + \frac{2\pi}{\lambda_M} \int_0^L [1 - \frac{\lambda_M}{\lambda} (\frac{c}{V_z} - 1)] dz$$
 (3)

and $\theta_{_{0}}$ is the initial phase of the electron with respect to the optical radiction field.

For a monochromatic beam of electrons the energy transfer characteristics of a FEL oscillator may best be described in terms of its moments $\delta\gamma^{R}$ averaged over initial phases:

$$\frac{1}{6\sqrt{3}} = \frac{1}{2\pi} \int_{0}^{\pi} (6\gamma)^{3} d\theta . \tag{4}$$

Results of numerical integrations 2 $\overline{b\gamma}$ and $\overline{b\gamma}^*$ for the present Stanford FEL zuplifier operating at an optical power density of $S = 10^5$ watts/cm² is shown in Figure 2. The figure shows the dependence of $\overline{\delta\gamma}$ and $(\overline{b\gamma}^2)^{1/2}$ as a function of input electron energy measured with respect to the resonance energy. The resonance energy γ_R is defined as that input castly for which $\overline{b\gamma} = 0$. Analytically γ_R can be evaluated by letting the degreent of the integral in eq. (3) be equal to zero and solving for γ_R and subsequently for γ_R in terms of λ , λ_M and \overline{b}_M . The result is

$$\gamma_{R} = \left(\frac{\lambda K}{2\lambda} \left(1 + aB_{H}^{2}\right)\right)^{1/2}$$
 (5)

where a is a geometric factor for the periodic magnet and $B_{\rm H}$ is the RDS magnetic flux density in the strtic periodic magnet. For $\gamma \gtrsim \gamma_{\rm R}$, an electron on the average loses energy and as a result the EM wave is amplified. For $\gamma \lesssim \gamma_{\rm R}$, the electron gains energy from the optical radiation field leading to the attenuation of the FM wave. Quantum mechanically, these two processes correspond to stimulated emission and absorption of radiation respectively.

 $\frac{1}{2} \frac{d\delta \gamma^2}{d\gamma}$ and that there is a similarity in the functional dependence on energy of the second moment $\delta \gamma^2$ and the spectral power density for apontaneous radiation.

These results have been used in the present analysis to generate electron energy transfer characteristics for five different magnets operating below saturation. With this approximation 67 in eq. (2) can be written as follows:

$$\delta_{Y} = \overline{\delta_{Y}} + \sqrt{2} (\overline{\delta_{Y}^{2}})^{1/2} \cos(\theta_{o})$$
 (6)

where $\delta y = \frac{1}{2} \frac{d\delta y^2}{dy}$

The analytic expressions describing the various spontaneous radiation lineshapes used in the storage ring simulations are listed on Table I.

All ragnets were designed to have the same resonance energy $\gamma_R = 83.365 \text{ and maximum mean electron energy loss at } \gamma = \gamma_R + 0.1.$ In addition, the maximum value of $\delta \gamma^2$ for each magnet was adjusted in such a way that

$$\int_{-\infty}^{\infty} \left(\widetilde{\mathsf{d}} \tau \right)^2 \, \, \mathrm{d} \tau = \mathrm{KS} \tag{7}$$

where K is a constant obtained by calculating (7) for the magnet used at the Stanford FEL experiment. S is the optical power density. The dependence of $\overline{\delta \gamma}$ and $\overline{\delta \gamma}^2$ on input energy $(\gamma - \gamma_R)$ for the five lineshape simulations at S = 10⁵ watts/cm² is shown in Figure

THE PROPERTY OF THE PROPERTY O

5. The magnet with a sin x/x lineshape approximates quite well the present anguet used at Stanford and whose emergy trensfer characteristics are illustrated in Figure 2.

Equations of Motion

If the energy γ_n of the electron is measured at point A (see Fig. 1) just before the FEL oscillator, then after one complete revolution moving counterclochrise, the energy γ_{n+1} is given by

$$Y_{n+1} = Y_n + d\gamma(Y_n, \theta_n) + V \cos\left[\frac{2\eta}{T}(r_n + r_g)\right] - 2\frac{(Y_{n+1} - Y_g)}{M_g}$$
 (8)

where $\delta \gamma(\chi_n,\theta_n)$, given by either eqs. (2) or (6), is the energy (measured in units of ac²) gained by the electron from the FEL oscillator. $\delta \gamma$ depends on the initial electron energy and initial optical phase θ_n .

The third term on the right hand side of eq. (8) represents the caergy gained by the electron in the RF cavity. The emergy gained depends on the time of arrival $\tau_{\rm a} + \tau_{\rm b}$ of the electron at the RF cavity. Here $\tau_{\rm n}$ is the time distance between the arrival of the electron and the arrival of an ideal synchronous electron. The energy $\tau_{\rm b}$ and phase $\tau_{\rm b}$ of the synchronous electron is defined in the following way. Muving counterclockwise in Figure 1 from peint C to point B, the synchronous electron with energy $\tau_{\rm b}$ at C will arrive at point C, just before the RF cavity, at a time $\tau_{\rm g}$ such that the emergy gained from the RF cavity is equal to the average equilibrium emergy $\overline{\delta\gamma}$ lost to the FEL radiator. From eq. (1) at

equilibrius Ynel . Yn and

where T is the period of the NF field and V is the maximum energy that the electron can gain from the NF cavity.

The last term on the MS of eq. (8) describes the damping effect that synchrotron radiation has on the electron energy. In all of the storage ring simulation, it has been assumed that K_S = 50,000 turns.

The reference trajectory of the electron is assumed to be the ideal traj tory of the synchronous electron. With respect to this trajectory the fractional change in orbit length (revolution time) is proportional to the fractional electron energy deviation from the ideal synchronous energy. The proportionality constant a, annual by M. Sands¹ the dilation factor, is defined as

The change in time position t in one pass through the storage is then given by

$$\tau_{n+1} = \tau_n + \alpha t \frac{(\gamma_{n+1} - \gamma_S)}{\gamma_S}$$
 (9)

If the energy of the electron is measured with respect to the synchronous energy $(b\gamma = \gamma - \gamma_g)$, then the two coupled equations

describing the evolution of phace and energy of an electron in a fill storage ring are as follows:

$$\Delta Y_{n+1} = \Delta Y_n - 2 \frac{\Delta Y_n}{N_S} + \delta Y (\Delta Y_n, \theta_n) + V \cos \left[\frac{2\pi}{T} (\tau_n - \tau_S) \right]$$
 (10)

$$t_{B+1} = t_{A} + \frac{off}{\sqrt{s}} d\gamma_{B+1}$$
 (11)

The above non-linear equations of motion have been linearized and studied in detail by M. Sands for a gaussian lineshape

Mumerical Results

The full nonlinear equations of motion (0) and (1) were integrated manerically for the magnet lineshapes shown in Figure 3 and for various ranges of optical power density 5, dilation factor α , maximum energy gained from the RF cavity V, and synchronous energy Y_R. The most important results are listed in Table II.

All the simulations were made for M = 100,000 revolutions of the electron in the storage ring. A random number generator program written by G. Marsaglia, et al., from McGill University was used to initialize the optical phase of the electron on every turn just before interacting with the FEL.

After 100,000 revolutions in the storage ring simulation program, the performance of the various magnet lineshapes was evaluated in terms of the following quantities:

a). Equilibrium 1866 spread a of electron anorgy just before the FEL magnet

$$\sigma^2 = \frac{1}{R-1} \sum_{j=1}^{R} (\Delta r_j - \overline{\Delta r})^2$$

where it is the number of passes in the storage wing and

$$\overline{b\gamma} = \frac{1}{H} \sum_{J=1}^{H} b\gamma_J = \frac{1}{H} \sum_{J=1}^{H} (\gamma_J - \gamma_g)$$

is the equilibrium mean value of the energy measured with respect to the synchronous energy just before the FEL.

For all magnet lineshapes, σ had very little dependence on Y and σ over the ranges of 0.01 + 0.11 and 6.02 + 0.1 respectively. Increasing the optical power density from $S=10^4$ watts/cm² to $S=10^5$ watts/cm² did not increase the equilibrium spread σ by more than a factor of 2. However there is a strong dependence of σ on γ_S as shown in Figure 4 for the gaussian lineshape simulation at $S=10^5$ watts/cm².

The minimum energy spread occurs for γ_S = γ_R and it increases monotonically for γ_S > γ_R . The apparent leveling-off of or t γ_S = γ_R = 0.4 is an indication that the total number of passes M = 100,000 were not sufficient to generate an equilibrium value for 0. However, the effective damping time N_D has increased abrujtly indicating that the energy and phase oscillations are still increasing and equilibrium has not been reached.

One general conclusion about o for the magnet lineshapes analyzed is that the minimum attainable equilibrium value of o

is always as large, or larger than the gain-absorption width of the magnet lineshape.

) Mean energy M lost by the electron to the FEL:

where γ_J^A and γ_J^B are defined as the energy of the electron just before and just after the FEL (see Figure 1) respectively during the Jth pass of the electron in the storage ring simulation. All is, of course, the mean energy gained per electron b, the radiation field in the FEL optical cavity. The average power converted into radiation by a beam of electrons is $\overline{bl} = c^2$ (1/e) where I is the average electron current in the storage ring.

 $\overline{\Delta I}$ showed approximately the same behavior as σ as a function of α , V and S. The maximum amount of average energy $\overline{\Delta I}(\gamma_{gk})$ that could be extracted from the electron occurred for values of γ_g somewhere in the range between γ_g and $\gamma_g+0.1$ depending on the particular FEL magnet design. The ranges of maximum output laser power varied from a minimum value of 7.5 matts/ampere for the perabolic lineshape simulation to 25 watts/ampere for the sin x/x liaeshape simulation.

c) Equilibrium 1995 time spread tags

$$T_{2000}^2 = \frac{1}{1-1} \int_{-1}^{1-1} \frac{1}{J_{0,1}} \left(\tau_3 - \overline{\tau} \right)^2$$

$$\overline{\tau} = \frac{1}{H} \int_{-2\pi}^{1-1} \tau_3 ...$$

Tops represents the time length of the electron bunch in the itorage ring. For all lineshape simulations τ_{RMS} increased with τ_s , decreased with τ_s as shown in Figure 5. The period of the RF field was chosen to be T = 40 x 10^{-9} src. The ranges of final equilibrium bunch lengths in the ctorage ring were from a maximum of 16° to a minimum of 1° .

d) Energy damping M_D

The discrete energy autocorrelation functions $\{A_{\underline{k}}\}$ was evaluated as follows:

where M is the number of equally spaced samples of the energy by of the electron for one complete simulation record of 100,700 passes. The value of by was sampled every 100 revolutions yielding a total number of samples M = 1000. All the coefficients (A_K) of the energy autocorrelation functions were plotted and an effective damping time M_D was graphically estimated for all storage ring simulations.

To understand the dynamic processes involved in generating the equilibrium energy and phase distributions of the electron, it is convenient to divide the energy domain accessible to the electron into two regions: a) the synchrotron radiation damping region and b) the FEL damping region. Figure 6 shows a plot of the derivative $\frac{d\delta \widetilde{Y}}{\delta \gamma}$ as a function of $(\gamma \gamma_{\widetilde{Y}})$ for the Stanford FEL magnet shown in Figure 2. $\frac{d\delta \widetilde{Y}}{\delta \gamma}$ is identified as the megative

of the average electron energy damping rate. Maximum damping rate occurs when the electron energy is near the resonance energy $\gamma - \gamma_R = 0$ of the FEL magnet. The damping rate decreases for $\gamma - \gamma_R > 0$ and becomes negative (antidamping) for $|\gamma - \gamma_R| > 0.1$. $|\gamma - \gamma_R| > 0$ and becomes negative (antidamping mechanism is synchrotron radiation. The value of $\frac{d\delta \gamma}{d\gamma}$ for synchrotron radiation is trom radiation. The value of $\frac{d\delta \gamma}{d\gamma}$ for synchrotron radiation is $\frac{d\delta \gamma}{d\gamma} = -1/N_D = -2 \times 10^{-5}$ and is shown as a broken line in Figure 6.

In addition to damping energy oscilfations the FEL excites random electron energy fluctuations resulting from the random values of optical phase with which the electron enters the interaction region. The spread of the fluctuations $(\overline{6}\gamma^2)^{1/2}$ are shown in Figure 2 as a function of input energy Y-Yg.

Equilibrium in the storage ring is reached when the rate at which random energy fluctuations generated by the FEL equals the rate at which the energy fluctuations are damped by the FEL and by synchrotron

radiation

A typical simulation of energy and phase evolution in an FEL storage ring is illustrated in Figure 7. The black dots represent the energy of the electron and the solid triangles represent the phase of the electrons as a function of the revolution number in the simulation. The two figures shown illustrate qualitatively how synchrotron radiation energy damping and energy damping from the PEL contribute to decrease the amplitude of the large synchrotron oscillations. The upper figure describes the evolution of the electron energy and phase for the first 1200 revolutions. The maximum energy excursion by the electron is about Y-Y_S = x 0.8. The two horizontal dotted lines

shown above and below the synchronous energy bound the region of yell positive energy damping. The energy and phase oscillate in a nearly perfect sinusoidal motion. However, there is a slow attentuation of the oscillations originating from synchrotron radiation damping (N_S = 50,000 turns). Both the average energy damping rate and energy fluctuations excitation rate by the FeL make a negligible contribution to the energy and phase motion of the electron during the first 10,000 turns. Even though the electron is swept through the energy interaction region of the FeL during each synchrotron oxcillation the changes in energy produced by the RF cavity are too large and as a result the number of revolutions that the electron spends within the damping region of the FEL is too small compared to the total number of revolutions required to complete one synchrotron oscillation.

synchrotron radiation to amplitudes comparable to the energy width of the FEL interaction region the electron spends a larger portion of the synchrotron oscillation in the positive damping region of the FEL. As a result, the energy motion is more effectively damped by the FEL. The lower trace in Figure 7 illustrates this effect. After 11,400 passes the amplitude of the synchrotron oscillation is decreasing at a much faster rate than that shown in the upper trace. Also, when the same system was initialized close of its synthronous condition ($\gamma = \gamma_S$, $\tau = 0$) the energy and phase oscillations grew from zero amplitude to its final equilibrium values after approximately 1200 passes. Almost identical results were obtained when the FEL energy transfer characteristics were computed using Eqs. (2) and

13

(3) or when using the small signal approximation of Eq. (6).

when the damping term $\overline{\delta \gamma}$ in Eq. (6) was set to zero the system was not able to reach equilibrium in 100,000 passes. In fact, the ability of the system to reach equilibrium was tested for various non real relative ratios of $\overline{\delta \gamma}$ to $(\overline{\delta \gamma}^2)^{1/2}$ in Eqs. (6). The results indicated that the equilibrium configurations of the system was very sensitive to this ratio. For example, increasing the value of the damping term $\overline{\delta \gamma}$ by a factor of 2 resulted in a final equilibrium energy spread smaller than 1/2 the width of the gain curve, with the electron almost completely constrained to have energies within the linear region of the gain curve, and as a consequence of this the final equilibrium state was approached at a much faster rate than in the real case (N_D < 500 passes).

The triangular lineshape simulation was the most effective in damping energy sscillations (N $_{\rm D}$ = 3300 revolutions at S = 10^5 watus/cm²). At S = 10^4 watts/cm² the Lorentzian lineshape showed the least amount of energy damping (N $_{\rm D}$ > 25,000 revolutions). This was expected, since the maximum slope of the Lorentzian lineshape gain curve has the smallest value of all the magnet lineshapes

The dependence of energy damping $1/N_D$ on synchronous energy γ_S is shown in Figure 4 for the sin (x)/x lineshape simulation. As the value of $(\gamma_S - \gamma_R)$ increases beyond the width of the FEL $\overline{6\gamma}$ - VS - $(\gamma - \gamma_R)$ curve the damping rate $1/N_D$ decreases and becomes nearly equal to the synchrotron damping rate $\frac{1}{N_S} = \frac{2 \times 10^{-5}}{REV}$ at

 $(\gamma_S - \gamma_R)$ = 0.45. This result is in agreement with the previously discussed picture where the damping of electron energy by the FEL is very small when the energy amplitude of synchrotron oscillations is larger than the energy width of the gain curve.

Conclusions

The results presented here indicate that the simple FEL magnet lineshapes studied in a storage ring do not provide efficient conversion of electron kinetic energy to laser radiation. The largest expected average power attainable from a storage ring FEL laser is of the order of tens of watts per ampere of stored electron beam current.

Research work is underway at Stanford University to study other magnet designs which will hopefully increase the operating efficiency of a free electron laser in a storage ring.

LIST OF IMPORTANT SYMBOLS

- $\gamma = electron$ energy measured in units of ac.
- Y_S = synchronous electron energy.
- Y = resonance electron mergy.
- $\delta\gamma$ = energy absorbed by electron from the $F\mathbb{C}_+$ optical radiation field in units of mc^2 ,
- $\Delta\gamma$ = energy of electron in a storage ring measured with respect to the synchronous energy in units of mc 2
- V = maximum increase in electron energy from the radio frequency cavity in units of ac^2 .
- t = time distance (in seconds) between electron and synchronous
 electron just before entering RF cavity.
 - t_S = time of arrival (in seconds) of synchronous electron at RF cavity.
- T = period (in seconds) of RF field.
- θ = optical phase (in degrees) of electron.
- M * total number of revolutions of the electron in the storage ring.
- N_S = synchrotron radiation energy damping time measured in number
- of revolutions.

 Mp = effective energy damping time of electron in FEL storage ting measured in number of revolutions.
- a dilation factor.
- g = equilibrium root mean square deviations (in units of mc²) of electron energy from the mean in the FEL storage ring.
- AT = equilibrium mean energy (in units of mc²) lost by electron to the FEL radiation field.

- S = FEL optical power density in units of watts/cm².
- A = wavelength (in meters) of optical radiation field.
- $\lambda_{\rm H}$ = wavelength (in meters) of FEL periodic magnetic field.
- B. BE magnetic flux density in FEL periodic magnet in units of weber/m².

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FIGURE CAPTIONS

- Fig. 1. Diagram of basic components of a free electron laser in a storage ring.
 - Fig. 2. Energy dependence of $\overline{\delta \gamma}$ and $(\delta \gamma^2)^{1/2}$ below saturation for the Stanford University FEL magnet.
- Fig. 3. Energy dependence of $\overline{6\gamma}$ and $\overline{6\gamma^2}$ for five different FEL magnet designs operating below saturation at S = 10^5 watts/cm².
- Pig. 4. Dependence of equilibrium RMS spread σ and effective energy damping constant $1/N_D$ on synchronous energy for the guassian lineshape simulation at S = 10^5 watts/cm 2
- Fig. 5. Dependence of equilibrium electron bunch length Type On RF cavity maximum electron energy gain V.
- Fig. 6. The solid line shows the energy dependence of the FEL damping rate $\frac{d\delta \gamma}{d\gamma}$ for the magnet shown in Fig. 1. The broken line shows the energy dependence of the damping rate $2/A_S = -\frac{d\delta \gamma}{d\gamma}$ for synchrotron radiation.
- Fig. 7. Typical energy and phase record for an electron in a FEL storage ring showing the damping of synchrotron oscillations during the first 1200 passes (top figures) and the damping of energy and phase oscillations by the FEL after 11,400 revolutions. The hurizontal broken lines bound the positive damping region of the FEL.

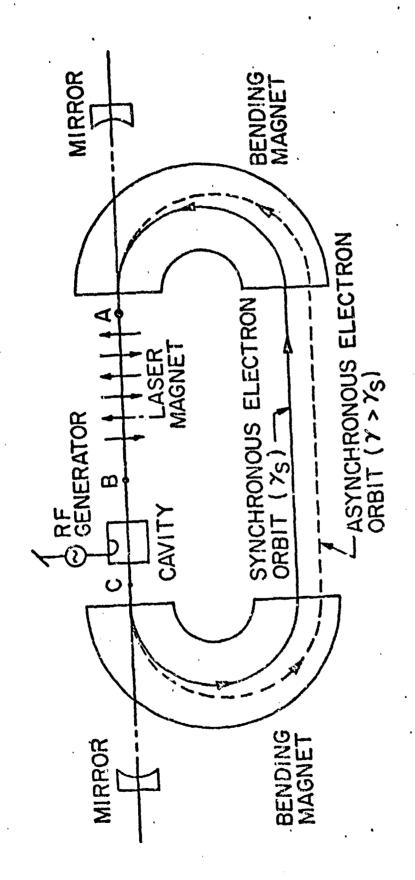


Figure 1

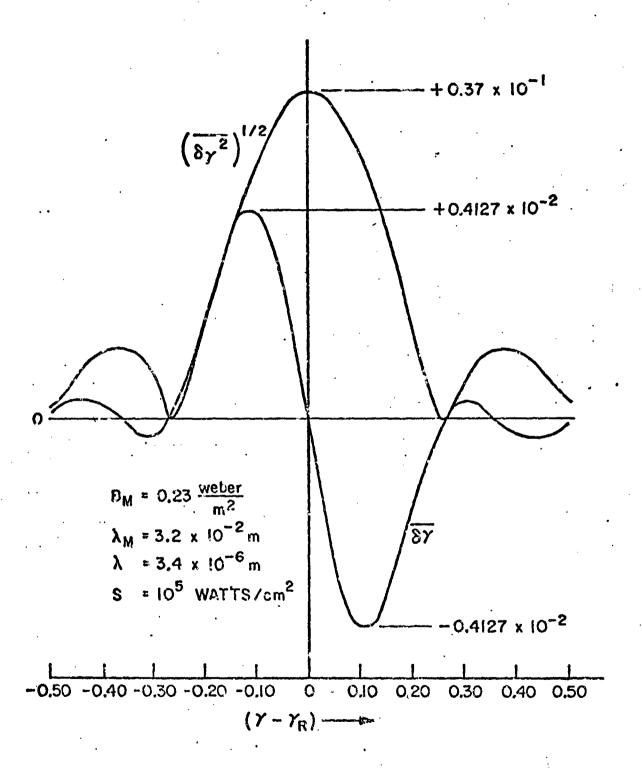


Figure 2

LINESHAPE SIMULATION

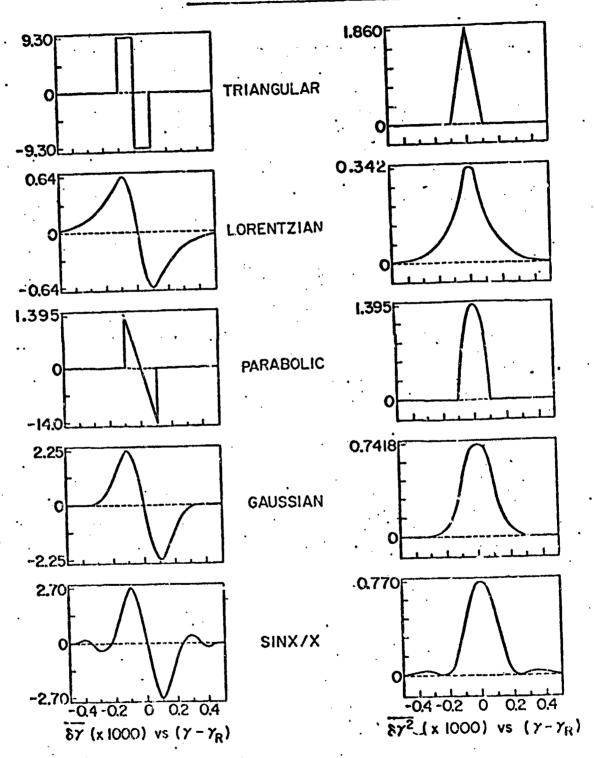


Figure 3

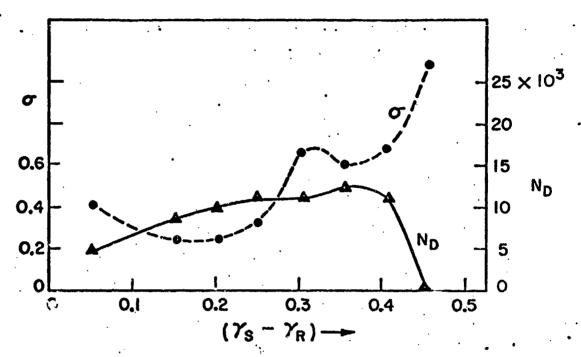


Figure 4

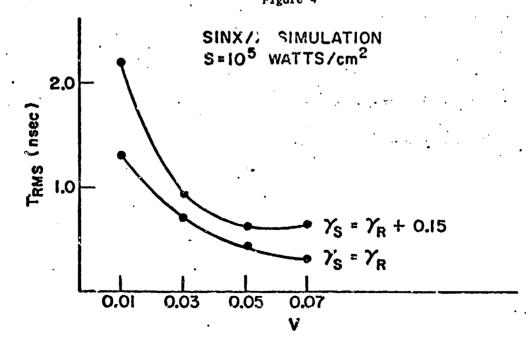


Figure 5

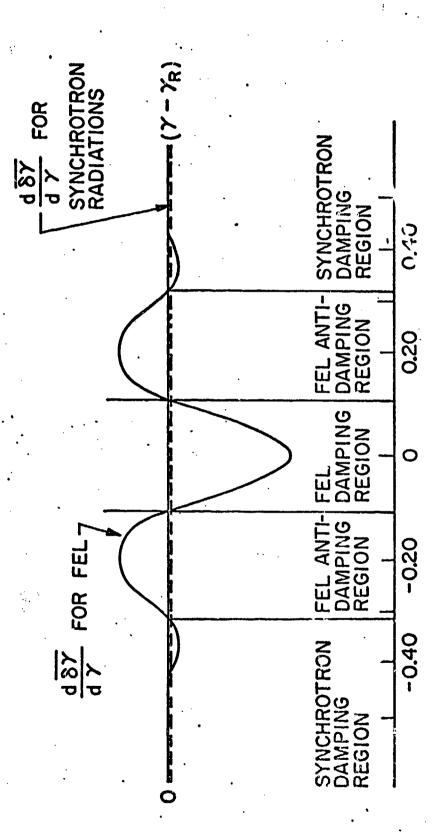
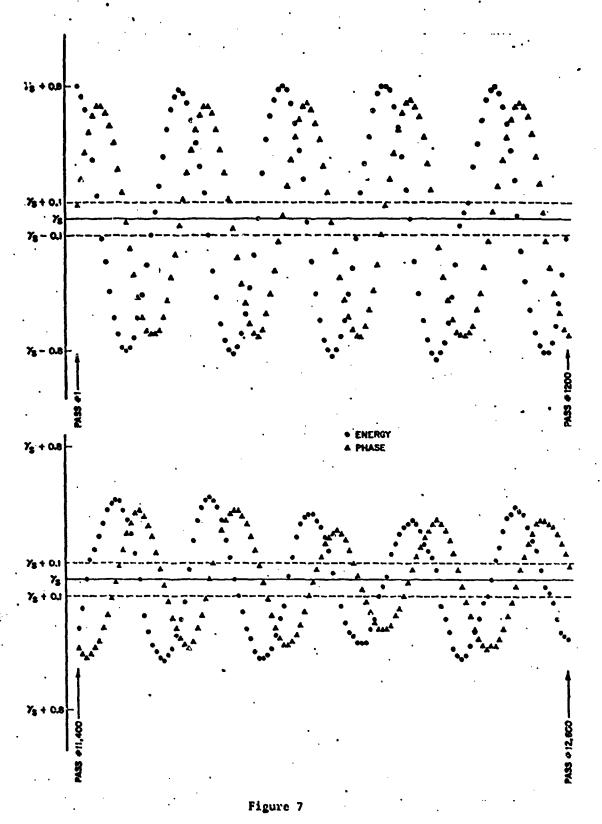


Figure 6



Lineshape $x = (\gamma - \gamma_R)/\delta$	۰.	+ 2 +	· 6 7	
Triangular	0.1	ж р [1 - x] 0 х - x = 0	$-\frac{x}{2b^{\frac{1}{2}}}$ $-\frac{x}{2b^{\frac{1}{2}}}$ 0	0 < x < 1 -1 < x < 0
Lorentzian	10	$\frac{\kappa}{\pi \Delta(1+\kappa^2)}$	$-\frac{\kappa\kappa}{\pi\Delta^2(1+\kappa^2)^2}$	* \ <u>*</u>
Parabolic	0.1	$\frac{3K(1-x^2)}{4\Delta}$	$\frac{3KX}{4\Delta^2}$. × × × × · ×
,aussian	10	Ke-x ² √π Δ	$-\frac{K \times e^{-X^2}}{\sqrt{\pi} \Delta^2}$	* > X
Sin x/x	.1	$\frac{K}{\pi\Delta} \sin^2(x)$	$\frac{x}{\pi \Delta^2} \frac{\sin(x)}{x} \left(\cos(x) - \frac{\sin(x)}{x}\right) x < \epsilon$	- sin(x) x < *

 $^{\dagger}_{K}$ = 1.86 × 10⁻⁹ S, where S is the optical power density in watts/cm².

TABLE II

Magnet Lineshape	Y _{SK}	σ ^{††}	हां (४८५)	מא
S = 10 ⁴ watts/cm ²			(x 10 ⁴)	(x 10 ⁻³)
Gaussian	83.565	0.260 ± 0.020	0.15 ± 0.06	24 ± 15
Parabolic	83.465	0.196 ± 0.017	0.16 ± 0.04	10 ± 1.6
Lorentzian	83.715	0.306 ± 0.050	0.13 ± 0.10	32 ± 13
sin x/x	83.415	0.250 ± 0.060	0.20 ± 0.20	16 ± 8
Triangular	83.415	0.195 ± 0.008	0.215 ± 0.46	7.8 ± 2.6
S = 10 ⁵ watts/cm ²				
Gaussian	83.565	0.404 ± 0.03	0.30 ± 0.05	6.8 ± 2.5
Parabolic	83.445	0.266 ± 0.04	0.153 ± 0.149	8.5±5
sin x/x	83.415	0.422 ± 0.07	0.46 ± 0.23	9.2 ± 2
		0.248 ± 0.06	0.38 ± 0.15	3.3 ± 1.4

 $^{^{\}dagger}\gamma_{\text{SM}}$ is the value of synchronous energy for which maximum optical power output $\overline{\delta \Gamma}$ (Y_{SM}) was obtained. $\uparrow \uparrow \sigma$ is defined as $(\Delta \gamma^2 - \overline{\Delta \gamma}^2)^{1/2}$.